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دفتر : أتمتة

Automation
للطالبة : حلا
للدكتور : مهند

اللجنة الأكاديمية لقسم الهندسة الصناعية

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Subject Automation and control system. Day Date

Keywords: Automation

Automation: mechanism for systems that move by itself, defined set of technologies, results in operation of machine without human intervention, achieve performance superior to manual operation in terms of ^{الطاقة} power, ^{الدقة} precision and speed of operation.

why does an automated system achieve superior performance compared to manual one?

- 1- more ^{دقة أعلى} precision
- 2- more ^{طاقة أعلى} energy and more ^{سرعة تشغيل أعلى} speed of operation

control: set of technologies achieves patterns of variations of operational parameters and sequences by providing the input signals

Automation system: include control system but the reverse is not true [control system parts of auto].

Main function of control system: ensure that outputs follow set points.

Functionality of Automation system: computing set points for control system, monitoring system performance, plant start-up or shut down, job and equipment.

Automation system are essential for most of modern industries.

example of an automated system contains a control system as a part of it: Robot.

We have Five major of Industrial IT context of industrial Automation:

Industrial Automation involves:

1- significant amount of hardware technologies related to instrumentation and sensing, Actuation and drives, electronics for signal conditioning, communication and display.

Industrial Automation system grow more sophisticated in term of knowledge and algorithms why?

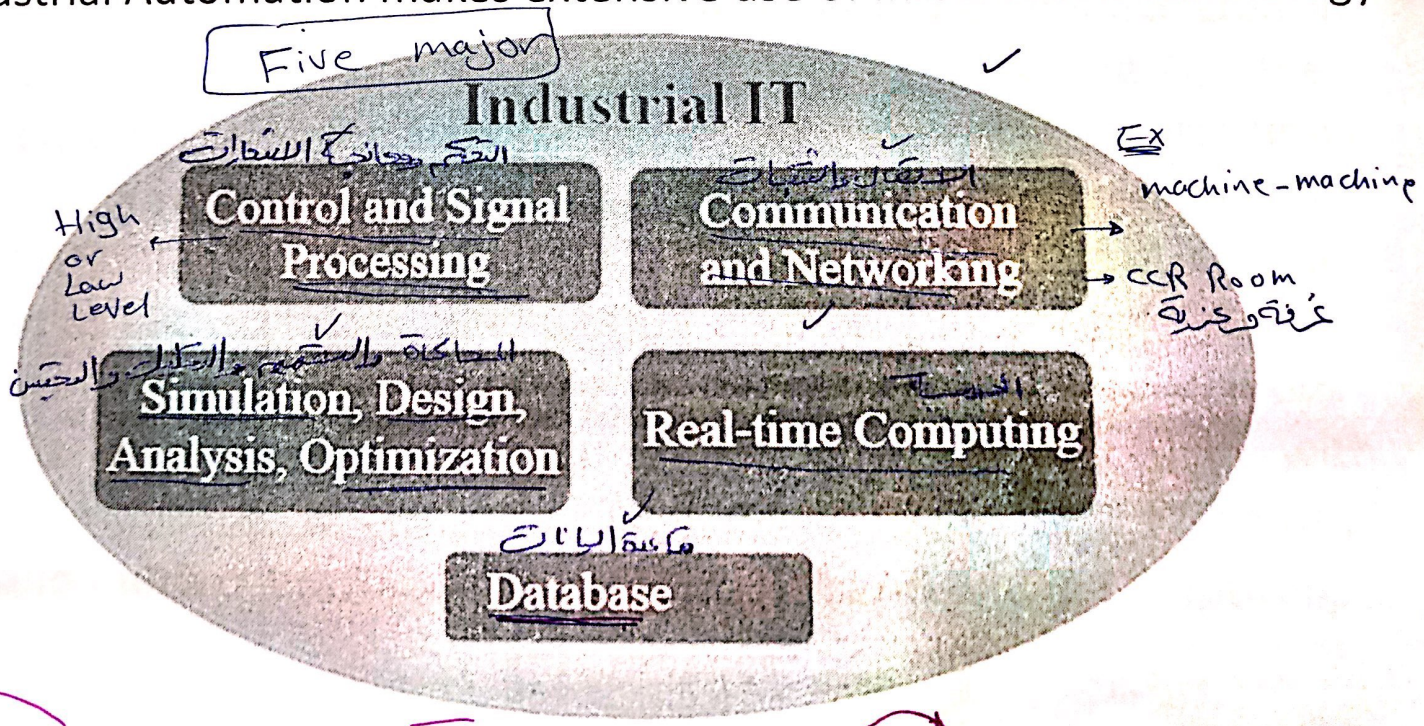
Because they encompass larger areas of operation comprising several units.

It is a part of industrial automation.

It is a part of machine automation.

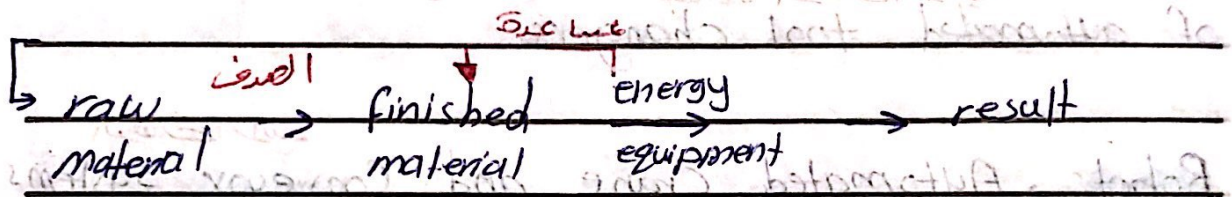
Industrial Automation vs. Industrial Information Technology

✓ Industrial Automation makes extensive use of Information Technology



Role of automation in industry:

Manufacturing process: produce finished product from raw/unfinished material using energy, manpower and equipment and infrastructure.



industry is essentially [systematic economic activity]
the Fundamental ^{الهدف الاساسي} objective of any industry is to make
it ^{الربح} profit.

profit = (Price/unit - cost/unit) $\times$ production volume

↳ good quality $\uparrow$ less cost $\downarrow$ less time $\downarrow$

Major parameters that affect cost/unit of a mass manufactured industrial product.

notes: major chip is controller and

تقريباً cost controller

The major factors that contribute to overall production time:

Cost/unit

Material

Energy

Manpower

Infrastructure

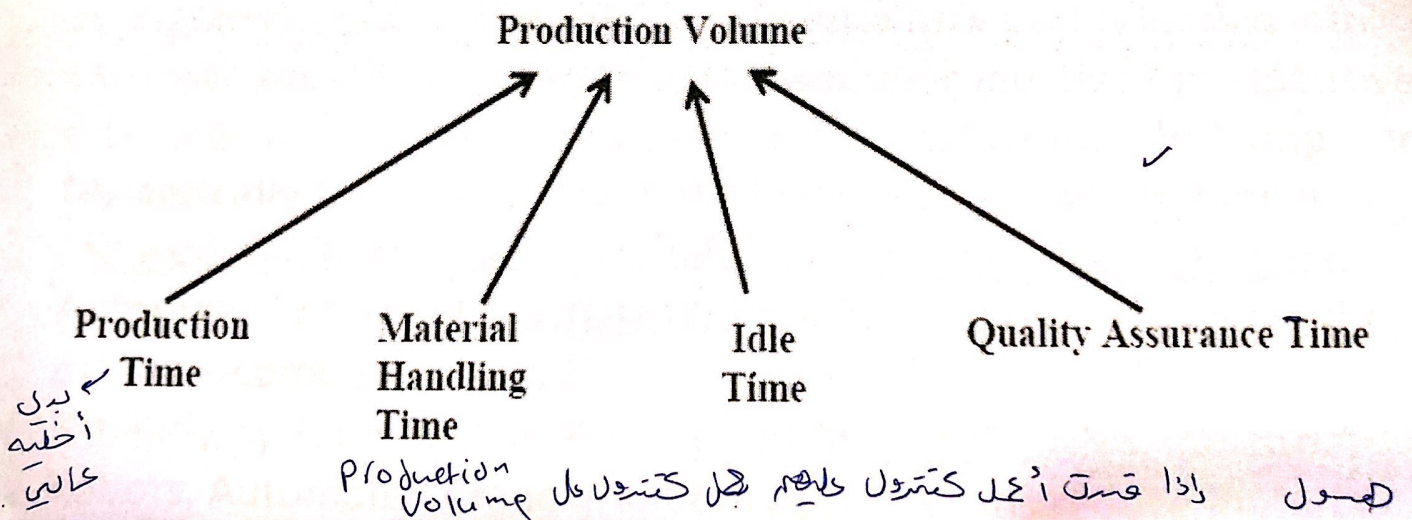
هذه هي المواد

الطاقة المستخدمة

↳ as amangement

هذه اذنا قدرات العمل كالماء والبرق والاعمال اليدوية

The major parameters that affect the cost/unit of
a mass-manufactured industrial product.



The major factors that contribute to Overall Production Time

Automated machine have significantly lower production times. ^{أوقات إنتاج أقل}

Numerically controlled (CNC): Machining centers setup time is reduced significantly with the help of automated tool changers. ^{مساعدة الأدوات الآلية}

Robots, Automated Crane and Conveyor systems reduce material handling time. ^{تقليل الوقت القابل مع الوقت}

Automation reduces cost of production significantly by efficient usage of energy, manpower and material.

The product quality that can be achieved with automated precision machine and process cannot be achieved with manual operations. ^{جودة المنتج}

^{اقتصادات الحجم}
Economy of scale: reduction in cost per unit resulting from increased production realized through operational efficiencies.

^{الآلية}
Automation facilitates economy of scale. it enable efficient large-scale production.

Economy of scope: The situation that arises when the cost of being able manufacture multiple products simultaneously proves more efficient than of being able manufacture single product at a time.

^{السرعة}
rapid programmability and reconfigurability of machines and process becomes a key requirement for commercial success.

Flexible Manufacturing: producing various products with the same machine.
Same machine to produce different product.

Economy of scope: most largely in electronic product manufacturing.

Types of production system

1- Continuous flow process: ^{الخط المستمر} Manufactured product it is in continuous quantities [The product not discrete ^{ليس كائن منفرد} object]. The volume of production is very high ^{حجم الإنتاج مرتفع} while the product variation is relatively low ^{تباين المنتج منخفض}.
example: ^{مصنع النفط} oil refineries, ^{مصنع الحديد والصلب} Iron and Steel plant, ^{الخرسانة} Cement and ^{الكيمياء} chemical plants.

2- Mass manufacturing of discrete product: ^{إنتاج منفرد} products are discrete objects and manufactured in large volume. ^{نوع المنتج محدود} Product variation is limited.
example: ^{الأجهزة} Appliances, ^{السيارات} Automobiles.

3- Batch production: The product is either discrete or continuous ^{يكون المنتج إما منفرد أو مستمر}. The variation in product types is larger than in continuous flow process. ^{التباين في أنواع المنتجات أكبر منه في العمليات المتدفقة}.
example: ^{الأدوية} pharmaceuticals, ^{مباني الحديد} Casting foundries, ^{نقود البلاستيك} plastic modeling, printing.

4- Job shop production: designed for manufacturing small quantities of discrete products which are custom built. ^{مطابق الطلبات الخاصة} example: ^{ورش الخياطة} machine shop, ^{مرافق الإنتاج} Prototyping facilities.

Types of Automation systems:

Based on Flexibility level of integration in manufacturing process

Automation system can be classified as:

1- Fixed Automation: used in high volume production with dedicated equipment which have a fixed set of operation and designed to be efficient.

Continuous flow + mass production use fixed Automation

example: Conveyors, paint Shop, transfer Lines.

A process using mechanized machinery to perform Fixed and repetitive operations to produce a high volume of similar parts.

2- Programmable Automation: changeable

Sequence of operation and Configuration of machines using electronic control.

Programmable Automation → Batch process

job variety low and mass production product volume is medium to high

3- Flexible Automations used in Flexible manufacturing systems (Fms) which is variably computer controlled.

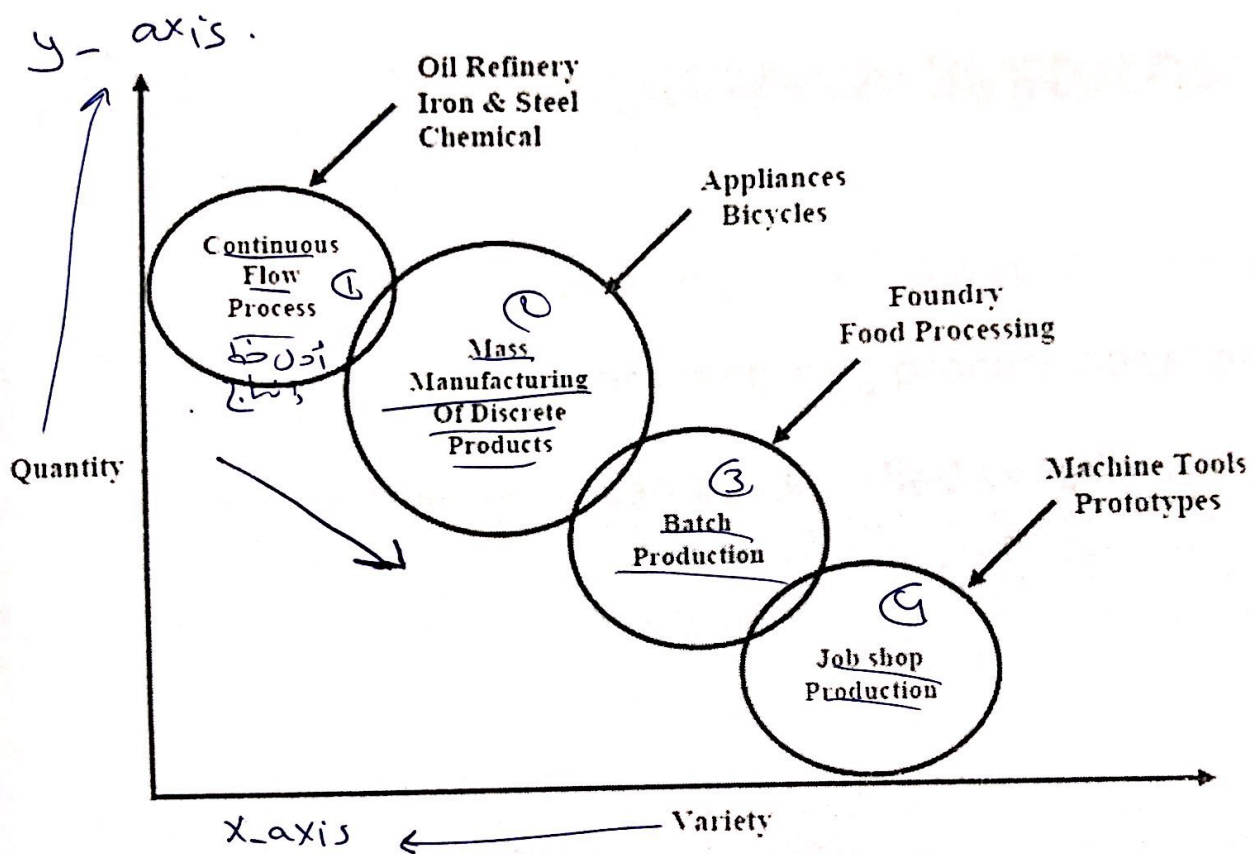
Flexible Automation $\left\{ \begin{array}{l} \rightarrow \text{job shops} \\ \rightarrow \text{batch process} \end{array} \right.$
product varieties are high and job volumes are medium to low

Flexible Automation (job shop and batch) use multi purpose CNC machines, Automated Guided Vehicles (AGV).

4. Integrated Automation: Complete Automation of manufacturing plant with all process functions under computer control and under coordination through digital information processing.

Integrated Automation: Include technologies such as computer aided design and manufacturing, computer aided process planning, computer numerical control machine tools, flexible marking system.

Integrated Automation: It's full integration of process and management operation using information and communication technologies.



Types of Production Systems

- Continuous Flow Process
- Mass Manufacturing of Discrete Products
- Batch Production
- Job shop Production

Example Integrated Automation: CIM [Computer Integrated Manufacturing]

Basic element of an automated system:

- 1- power [to accomplish the process and operate the automated system]
- 2- program of instructions
- 3- control system

Two Type of power to Accomplish the Automated system process.

- ↳ power for process power for Automation
- 1- to drive the process and controller unit itself
 - 2- to load and unload the work unit
 - 3- transport between operations.
- 2- Data and information processing.

* The principle power source.

- 1- widely available at moderate cost.
- 2- can be readily converted to alternative forms, mechanical, thermal, light
- 3- low level power can be stored in long life batteries

There are 6 examples of automated work cycles in which decision making is:

- 1- Operator interaction
- 2- Automated teller machine.
- 3- Different part or product styles processed by system.
- 4- Robot welding cycle for two doors vs four door car models
- 5- Variations in the starting work unit
- 6- Additional machining pass for oversized sand casting.

Two types of control system:

- 1- Closed loop system: operates with the feedback loop.
- 2- Open loop system: operates without feedback loop.

open loop system: → Simpler and less expensive.
→ Risk that the actuator will not have intended effect.

When to use an open loop control system?

- 1- Actions performed by control system are simple.
- 2- Actuating function is very reliable.
- 3- Any reaction forces opposing the actuation are small enough to have no effect.

- Advanced Automation Function:

- 1- Safety monitoring
- 2- maintenance and repair diagnostics
- 3- Error detection and recovery.

* Reasons for safety monitoring:

- 1- to protect workers and equipment.

* possible responses to hazards:

- 1- Complete Stoppage of the system.
- 2- Sound an alarm.
- 3- reduce operating speed of process
- 4- take corrective action to recover from safety violation.

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Maintenance and repair diagnostics

1- Status monitoring: monitors and records status of key sensors and parameters during system operation.

2- Failure diagnostics: Invoked when a malfunction occurs.

purpose: analyze recorded values so the cause of the malfunction can be identified.

Error Detection and Recovery

وظائف المراقبة

1. Error detection – functions:
 - Use the system's available sensors to determine when a deviation or malfunction has occurred
 - Correctly interpret the sensor signal
 - Classify the error

2. Error recovery – possible strategies:

- Make adjustments at end of work cycle
- Make adjustments during current work cycle
- Stop the process to invoke corrective action
- Stop the process and call for help

١- إجراء تعديلات في نهاية دورة العمل

٢- إجراء تعديلات أثناء دورة العمل

٣- توقف العملية لاستدعاء إجراء تصحيحي

٤- توقف العملية، طلب المساعدة.

Levels of Automation

مستويات
البيعة

1. Device level – [actuators, sensors, and other hardware components to form individual control loops for the next level] ✓
2. Machine level – [CNC machine tools and similar production equipment, industrial robots, material handling equipment]
3. {Cell or system level} – [manufacturing cell or system]
4. {Plant level} – factory or production systems level
5. Enterprise level – corporate information system

Management decisions can be either
"instinctive or structured"

1- Instinctive decisions :
pros / إيجابيات
rapidity and flexibility
cons / سلبيات

- no quantitative model
- limited number of alternatives
 - limited understanding of decision criteria.

Drawbacks can be extremely critical if
decisions are complex.

2 - structured decisions :
"based on quantitative model"
pros / إيجابيات

- Better understanding of the problem.
- Consideration of all possible alternatives.
 - precise decision criteria

* optimal decisions can be taken even for
complex problems.

Cons: Cons

- getting a mathematical model of a decision and ~~and~~ ~~here~~ problem might be time and resource consuming.
- trade-off between time/resources for decision-making and benefits of optimality.

PLC

A programmable logic controller: is a unit of hardware used to control and automate an industrial process.

- They were initially designed to replace hardwired relay-based control.

- PLC are used to solve control problems from [simple to complex].

essential components in PLC is:

- 1- input (push button)
- 2- output (the voltage applied to machine)

- Picture 4.1

Three main aspects of programmable logic

controller (PLC):

- 1- Input: connected to sensor device that informs PLC about environment.
- 2- output: connected to equipment need to be controlled.
- 3- Control diagram: uses set of logical instructions that drives the output based on input.

picture 5.0 input and output device. A

A relay : device that responds to voltage change by activating a switch.

- The contactor is used for high current.

Two common types of programmable logic controller or plc.

1- single box type

2- modular or rack type

- The box type is smaller and used for simpler control situations.

- The modular type consists of central rack that house various modules such as power supply processor, analog or digital input and output and communications, and special function modules.

- I/O modules can be much more specialized than that of box type, used for larger and more complex operation.

Typical plc Application 8.0

- example of popular use for plc: conveyor
why? because it involves intricate use sensor
and motors, also has need of complex logic.
- Industrial equipment use three phase power
for various reasons such as cost, size, durability

The converter has three contacts:

- 1- Two are connected to 220V AC source.
- 2- other connected to a starting capacitor and a push button

The Three phase converter has a motor that needs to be started via a starting capacitor.

The Pressure sensor would feed information in a 1- Timer 2- Counter

hardware ↑ ↑
→ start relay
- relay logic → Timer relay

How we control without plc?

The switch and momentary push button have been replaced with start and stop button.

- A Solenoid is powered to keep valve shut.

- A Solenoid another type of relay.

The pressure sensor would feed information in a Timer and counter.

Instead of large amount of devices and the resulting complicated wiring one piece of hardware plc can take place of all 20 timers and counters.

plc replace all wiring and individual pieces of hardware like counters, timers and relays.

plc is a special microprocessor based controller. It has Programmable memory that is used to store programs that instructs plc to how control machine or process.

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Input —||— normally open "I"

—||— normally close

output () "Q"

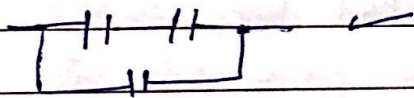
—||— نبشوف المكون اللى حيز وهرنا قاطبة من عليه قوت لفت

—||— output اللى حيز

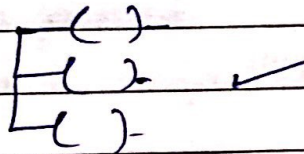
1] —||— () X

2] —||— () ✓

Input can be parallel and series.



Output just parallel.



examples:

1- If "Start" push button is pressed and a work piece is available at the beginning of the conveyor belt, the conveyor belt actuated until lift your finger.

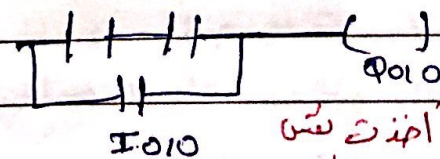
Start → بتقبل شغالة مادام
فتت كاسبة عليها

latching → توصيل parallel
ال input اللى address

لتنق output

I1.0 I0.0 Q0.0

بما لكسبها
انق مر التيار

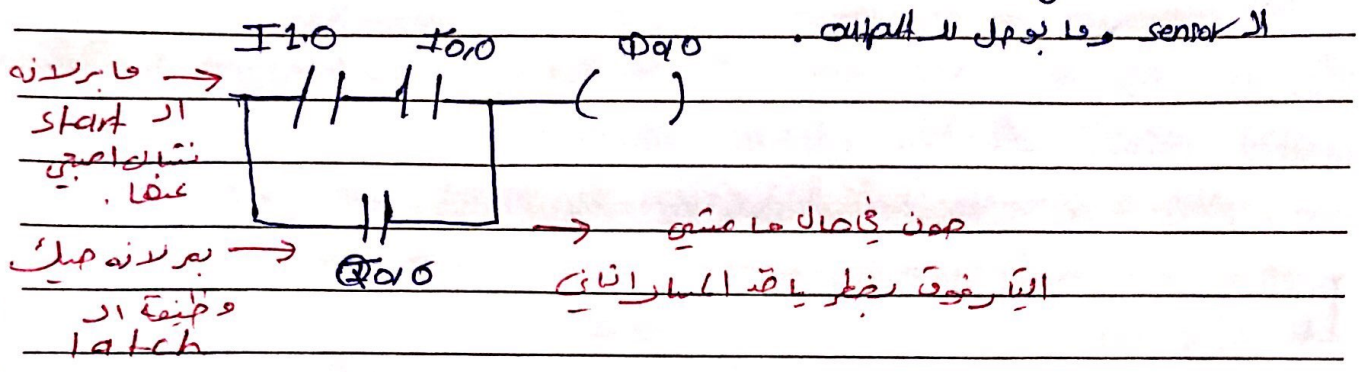


I0.0

انق تفت
Address

S T A R S N O T E B O O K

هذا مبدأ ال Latching مبدأ تشغيل عند start فإنتاج يقرئ

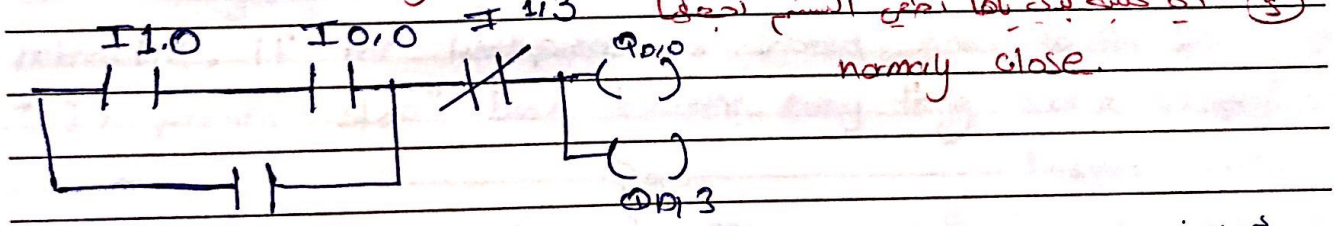


example 2

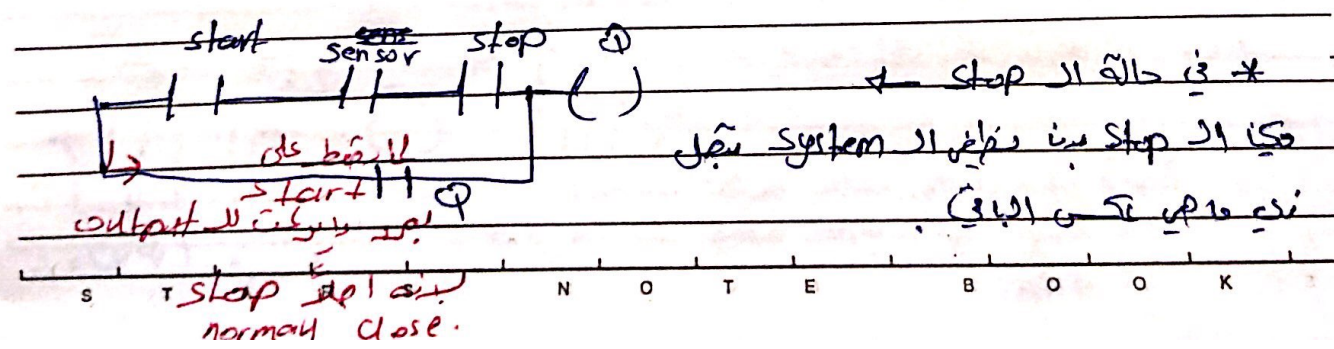
IF "Start" push button is pressed ^{series} and a ^{sensor} workpiece is available at the beginning of the ^{sensor} conveyor belt, the conveyor belt and the ^{sensor} clasper will be actuated until "reset" push button ^{latch} is pressed.

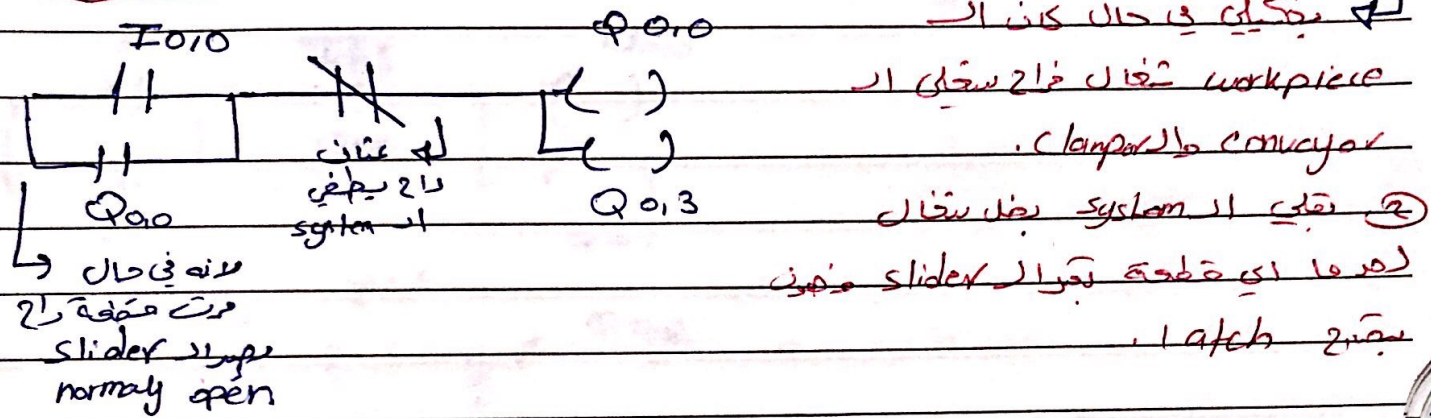
1) بدء احدث start وال work piece وال conveyor belt وال clasper
2) بهم نظام تشغيل لقر اكبس الى Reset

بالطبع أغلب ال address مبرمجين على انهم normally open والعكس ال stop

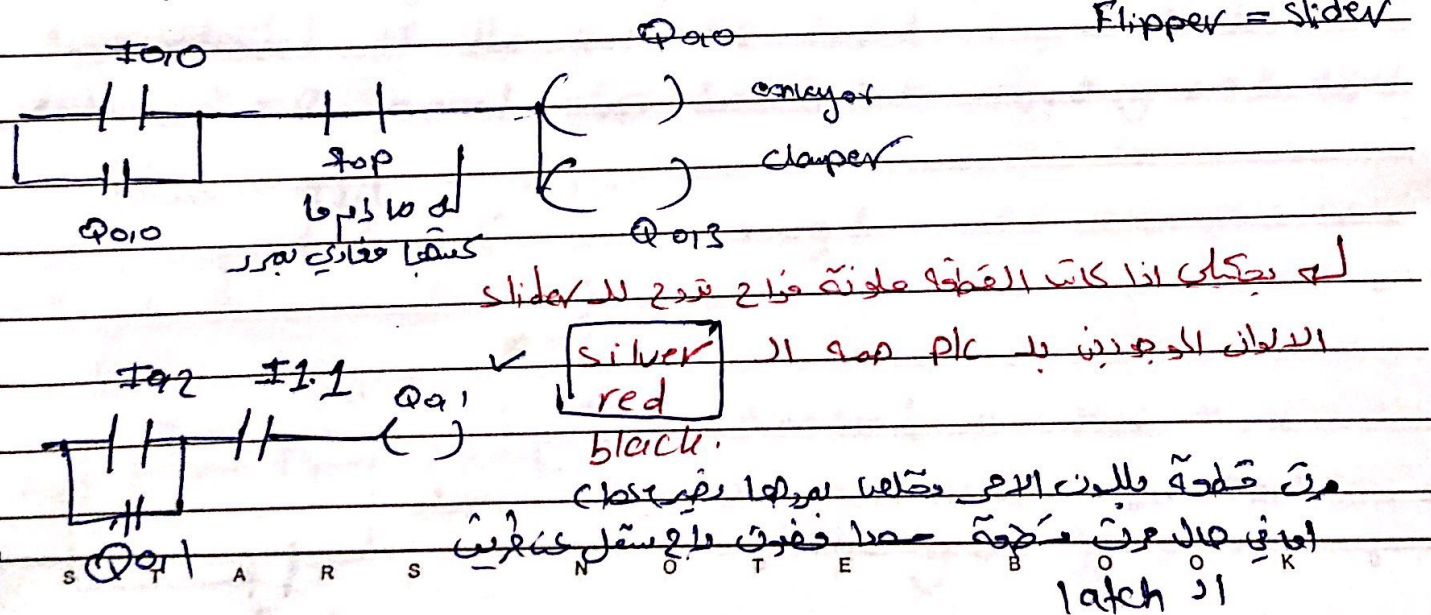


اولا اشئ كسبنا start فترت القطعة عند ال sensor وال reset الموجودة تغير استمرها لما اكسبها بس لما اشئ اصبى عند ال start يظل يعمل ستر لا output فمكون مؤقتة ال latch مبرمج



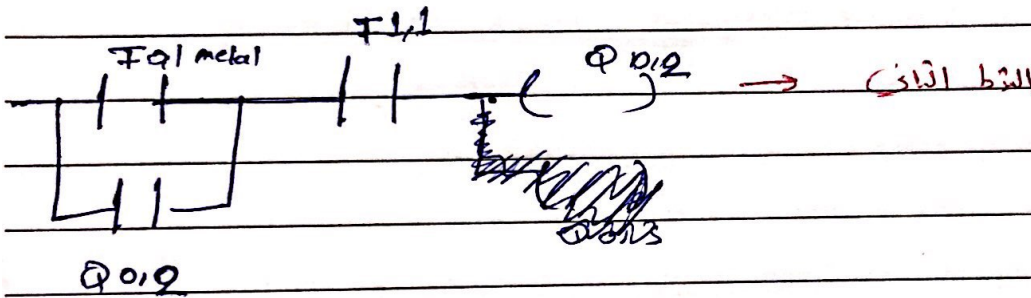
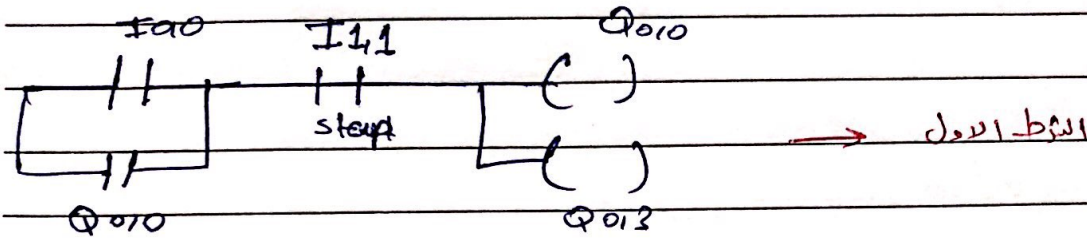


IF a workpiece is available at the start of the conveyor belt,
the conveyor belt is activated directly and the clamper have
retracted, IF the workpiece is colored, goes to the first slider
* IF pressed "stop" bush buttons every thing will be stopped.



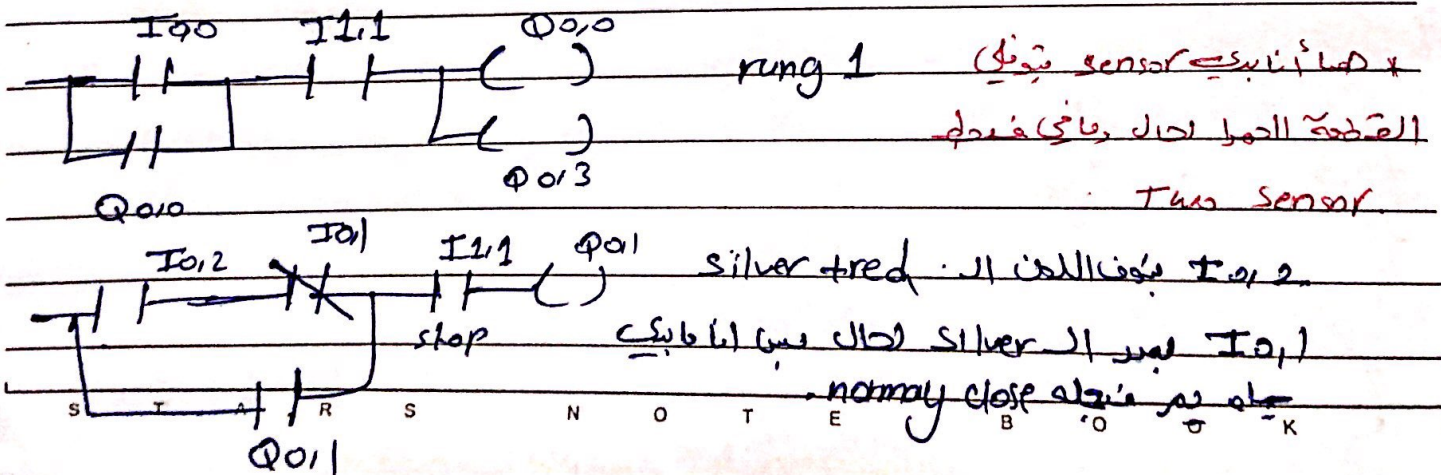
Example 5

IF a ^{sensor} workpiece is available at the start of the ^{sensor} conveyor belt the conveyor is activated directly and the ^{sensor} clammer have retracted. IF the workpiece is metal it goes to second slider. Q0.2
 "IF pressed stop" push button everything will be stoped"



Example 6

if a ^{sensor} workpiece is available at the start of the ^{sensor} conveyor belt, the conveyor is activated directly and the ^{sensor} clammer have retracted, IF the workpiece is red it goes to the first slider, "IF pressed stop bush button everything will be stoped



Input and Output Addresses

Address	Description	Identity
I0.1	Work piece is metal (silver)	Inductive proximity sensor
I0.0	Work piece is available at the start of the conveyor belt	Diffuse sensor
I0.3	Work piece is falling at one of any of the 3 sliders	Retro reflective sensor
I0.2	Work piece is black=0, Work piece is red or metal=1	Diffuse color sensor
I0.6	Second flipper is retracted	Inductive proximity sensor
I0.7	Second flipper is advanced	Inductive proximity sensor
I0.5	First flipper is advanced	Inductive proximity sensor
I0.4	First flipper is retracted	Inductive proximity sensor
Q0.2	Second flipper advances	Rotary cylinder
Q0.0	Conveyor belt	Permanent magnetic DC motor
Q0.1	First flipper advances	Rotary cylinder
Q0.3	Clamper retracts	Linear cylinder
I1.0	START	Push button
I1.1	STOP (normally closed)	Push button
I1.3	RESET	Push button